

Name: Solutions

Math 224 Exam 6
April 29, 2013

1. Consider the forced harmonic oscillator

$$\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + 17y = 0; \quad y(0) = 1, \quad y'(0) = 0.$$

(a) Is the system overdamped or underdamped?

The characteristic polynomial is

$$s^2 + 2s + 17, \quad \text{with roots } \frac{-2 \pm \sqrt{4 - 4 \cdot 17}}{2} \\ = -1 \pm 4i.$$

The system is therefore
underdamped.

(b) Suppose you hit the oscillating block with a hammer (on the spring side) at time $t = 3$, with total force 4. Modify the equation above to reflect this and then solve it.

Hitting the block on the spring side means a force is applied in the positive direction:

$$y'' + 2y' + 17y = 4\delta_3(t).$$

Laplace transform both sides:

$$s^2 \mathcal{L}[y](s) - s + 2s \mathcal{L}[y](s) - 1 + 17 \mathcal{L}[y](s) = 4e^{-3t}$$

$$\Rightarrow \mathcal{L}[y](s) = \frac{s+1}{s^2+2s+17} + 4e^{-3t} \frac{1}{s^2+2s+17}$$

$$= \frac{s+1}{(s+1)^2+16} + e^{-3t} \frac{4}{(s+1)^2+16}$$

$$= \mathcal{L}[\cos(4t)](s+1) + e^{-3t} \mathcal{L}[\sin(4t)](s+1)$$

$$y(t) = e^{-t} \cos(4t) + u_2(t) e^{-(t-3)} \sin(4(t-3))$$

- (c) How would your answer change if you hit it with the same force at the same time, but in the opposite direction?

This would only change the forcing function to $-4\delta_3(t)$: the solution becomes

$$y(t) = e^{-t} \cos(4t) - u_3(t) e^{-(t-3)} \sin(4(t-3)).$$

- (d) Show that either way, the velocity of the block is discontinuous at time $t = 3$.

Starting from the formula

$$y(t) = e^{-t} \cos(4t) + u_3(t) e^{-(t-3)} \sin(4(t-3)),$$

for $t \neq 3$ we get

$$v(t) = y'(t) = -e^{-t} \cos(4t) - 4e^{-t} \sin(4t)$$

$$+ u_3(t) \left[-e^{-(t-3)} \sin(4(t-3)) + 4e^{-(t-3)} \cos(4(t-3)) \right].$$

The last term is discontinuous at $t = 3$:

$$4e^{-(3-3)} \cos(4(3-3)) = 4, \text{ so}$$

$4u_3(t) e^{-(t-3)} \cos(4(t-3))$ has a jump

discontinuity at $t = 3$. The same term appears in the velocity of part (c), just with a - sign.

2. Consider the initial value problem

$$\frac{dy}{dt} = f(t, y) = 3t, \quad y(0) = 2.$$

(a) Using $\Delta t = \frac{1}{2}$, fill out the table below and give the resulting improved Euler's method estimate for $y(1)$:

k	t_k	y_k	$m_k := f(t_k, y_k)$	t_{k+1}	y_{k+1}^*	$n_{k+1} := f(t_{k+1}, y_{k+1}^*)$	$\frac{m_k + n_{k+1}}{2}$	y_{k+1}
0	0	2	0	$\frac{1}{2}$	2	$\frac{3}{2}$	$\frac{3}{4}$	$2\frac{3}{8}$
1	$\frac{1}{2}$	$\frac{19}{8}$	$\frac{3}{2}$	1	$\frac{25}{8}$	3	$\frac{9}{4}$	$\frac{28}{8} = \frac{7}{2}$

(b) Solve the initial value problem analytically and compute $y(1)$.

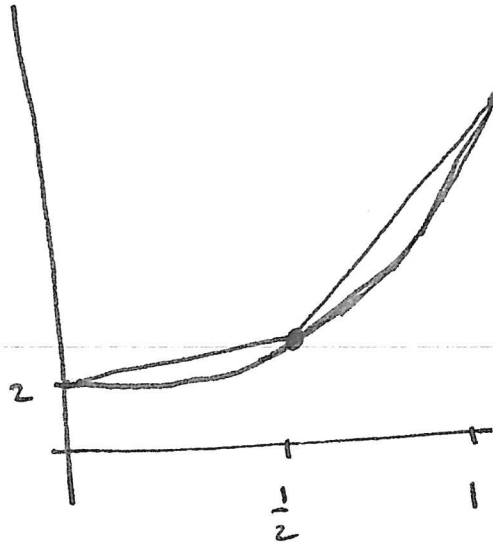
$$\frac{dy}{dt} = 3t \Rightarrow y(t) = \frac{3}{2}t^2 + C \quad y(0) = 2 = C$$

$$\Rightarrow y(t) = \frac{3}{2}t^2 + 2, \text{ and } y(1) = \frac{7}{2}$$

(c) What is the error in your approximation of $y(1)$?

$$y(1) - y_2 = 0.$$

- (d) Graph your approximation of the solution and the solution itself on the same axes.



- (e) Using our geometric derivation of improved Euler's method, explain why your approximate solution and your exact solution agree at $t = \frac{1}{2}$ and at $t = 1$ (but not in between).

Since the slopes m_0 and n_0 depend only on t , not on y , they are both the exact slopes of the curves, and so $\frac{m_0+n_0}{2}$ is exactly the average slope of the solution over $[0, \frac{1}{2}]$ (and similarly $\frac{m_1+n_1}{2}$ is exactly the average slope over $[\frac{1}{2}, 1]$). This means $y(t_1) = y_1$ and $y(t_2) = y_2$. But the approximate solution is piecewise linear, so it doesn't match otherwise.

Laplace transforms:

$$\mathcal{L}[y] = \int_0^{\infty} y(t)e^{-st} dt$$

$$\mathcal{L}[y'] = s\mathcal{L}[y] - y(0)$$

$$\mathcal{L}[y''] = s^2\mathcal{L}[y] - sy(0) - y'(0)$$

$y(t)$	$Y(s) = \mathcal{L}[y]$
1	$\frac{1}{s}$
e^{at}	$\frac{1}{s-a}$
$\sin \omega t$	$\frac{\omega}{s^2+\omega^2}$
$\cos \omega t$	$\frac{s}{s^2+\omega^2}$
$u_a(t)$	$\frac{e^{-sa}}{s}$
δ_a	e^{-as}
$u_a(t)f(t-a)$	$e^{-as}\mathcal{L}[f](s)$
$e^{at}f(t)$	$\mathcal{L}[f](s-a)$
$tf(t)$	$-\frac{d}{ds}(\mathcal{L}[f])$

Numerical Methods

Euler: $y_{k+1} = y_k + \Delta t f(t_k, y_k)$

Improved Euler:

- $m_k = f(t_k, y_k)$
- $y_{k+1}^* = y_k + (\Delta t)m_k$
- $n_{k+1} = f(t_{k+1}, y_{k+1}^*)$
- $y_{k+1} = y_k + (\Delta t) \left(\frac{m_k + n_{k+1}}{2} \right)$