

Name: Solutions

Math 224 Quiz 3 – E. Meckes

1. Consider the non-linear system

$$\begin{aligned}\frac{dx}{dt} &= y - ax^3 \\ \frac{dy}{dt} &= y - x,\end{aligned}$$

where  $a$  is a parameter:

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- (a) Identify the nullclines of the system. Then find all the equilibria of the system, and identify the value(s) of  $a$  at which the number and/or location of the equilibria changes.

$x$ -nullcline is where  $\frac{dx}{dt} = 0 : y = ax^3$

$y$ -nullcline is where  $\frac{dy}{dt} = 0 : y = x$ .

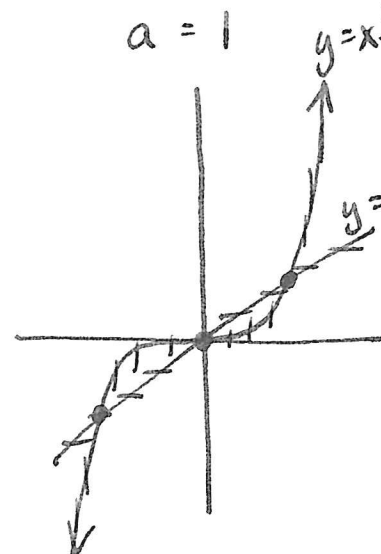
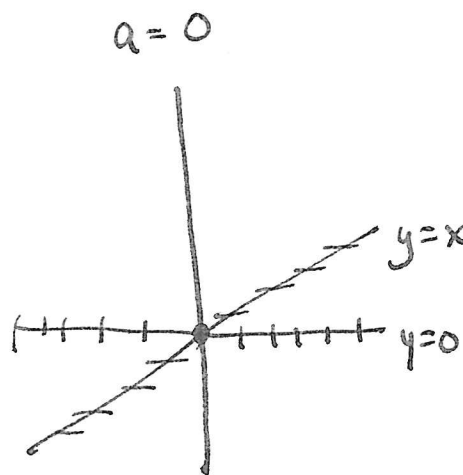
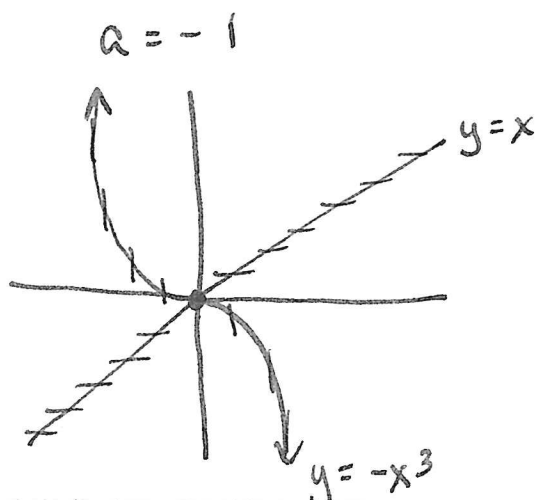
Equilibria are pts. of intersection of the nullclines:

$ax^3 = x$ . This is true if  $x=0$  (and then  $y=0$  as well)

or  $x = \pm \frac{1}{\sqrt{a}}$  (if  $a > 0$ ). So if  $a \leq 0$ , there is only the one equilibrium at  $(0,0)$ , and if  $a > 0$ , there are 3:  $(0,0)$ ,  $(\frac{1}{\sqrt{a}}, \frac{1}{\sqrt{a}})$ , and  $(-\frac{1}{\sqrt{a}}, -\frac{1}{\sqrt{a}})$ .

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- (b) Sketch the nullclines for  $a = -1$ ,  $a = 0$ , and  $a = 1$ . You do not need to draw arrows, just the nullclines themselves. Please label everything in your pictures!



The three choices of  $a$  correspond to three different systems - each should be drawn separately.

(c) For  $a = 1$ , compute the Jacobian of the system.

$$4 \quad J(x, y) = \begin{bmatrix} -3x^2 & 1 \\ -1 & 1 \end{bmatrix}$$

(d) Linearize the system at each of the equilibria and identify the type of equilibrium. You do not need to calculate eigenvectors.

$$6 \quad (0, 0) : J(0, 0) = \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix} \quad \text{Char. poly:}$$

$$\lambda^2 - \lambda + 1$$

Eigenvalues:

$$\lambda = \frac{1 \pm \sqrt{1-4}}{2} : \boxed{\text{spiral source}}$$

$$6 \quad (1, 1) : J(1, 1) = \begin{bmatrix} -3 & 1 \\ -1 & 1 \end{bmatrix}$$

Char. poly:

$$\lambda^2 + 2\lambda - 2$$

Eigenvalues:

$$\lambda = \frac{-2 \pm \sqrt{4+8}}{2} \quad \boxed{\text{saddle}}$$

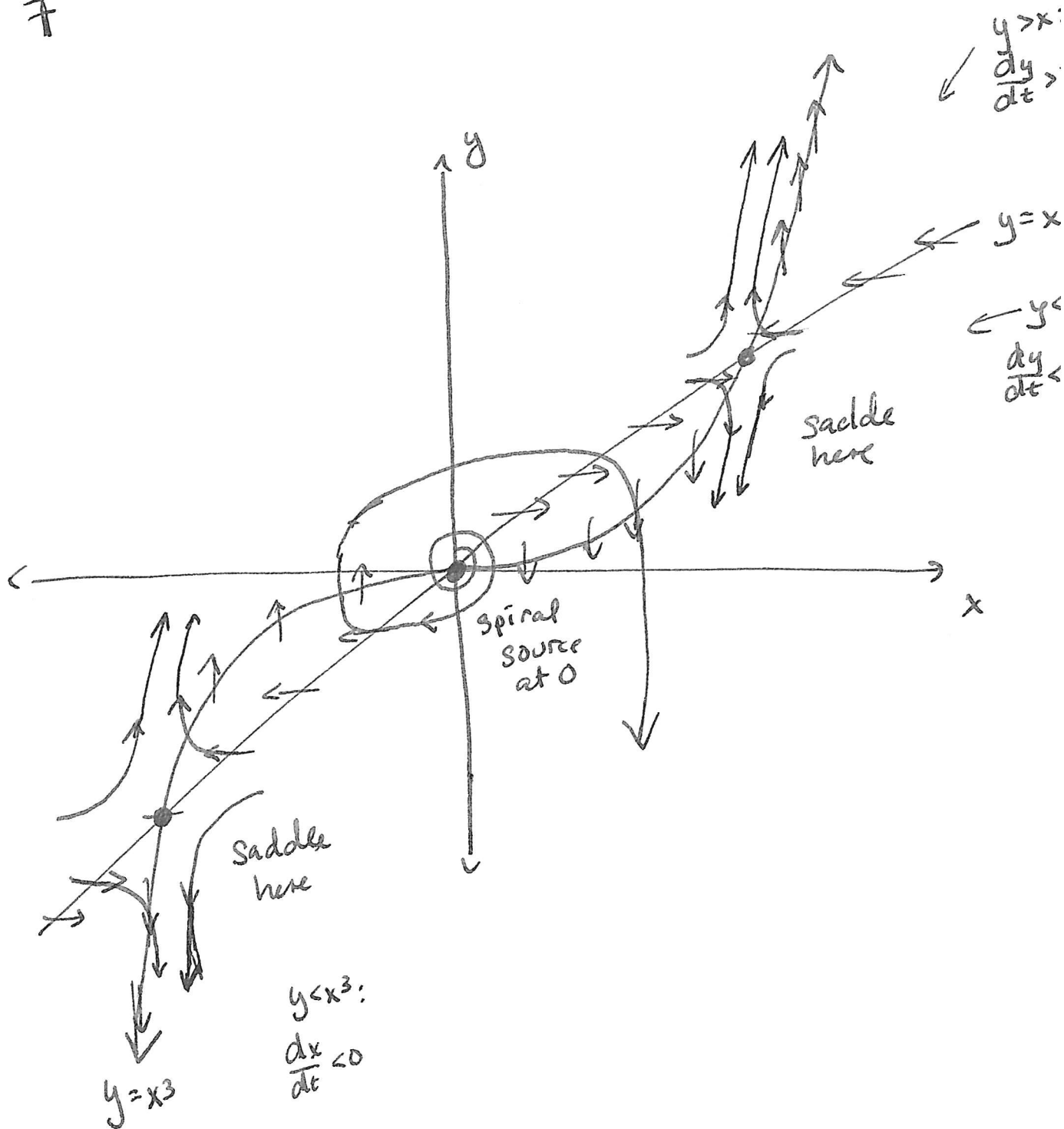
$$6 \quad (-1, -1) : J(-1, -1) = \begin{bmatrix} -3 & 1 \\ -1 & 1 \end{bmatrix}$$

(same as at  $(1, 1)$ )

$\boxed{\text{saddle}}$

(e) Sketch the phase portrait of the system with  $a = 1$ , making use of your answers to the previous parts. Again, you do not need to calculate eigenvectors.

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2. Consider the undamped, forced harmonic oscillator modeled by

$$\frac{d^2y}{dt^2} + 4y = 2 \cos(\omega t).$$

(a) If  $\omega \neq 2$ , find the general solution to the equation above.

15 Char. poly:  $\lambda^2 + 4$ . Ews:  $\lambda = \pm 2i$  3

$$\Rightarrow y_h(t) = k_1 \cos(2t) + k_2 \sin(2t) \quad 3$$

Complexify:  $y'' + 4y = 2e^{i\omega t}$ . Try  $y_c(t) = \alpha e^{i\omega t}$  1

$$\Rightarrow y_c'' + 4y_c = (-\omega^2 + 4)\alpha e^{i\omega t} \Rightarrow \text{take } \alpha = \frac{2}{4-\omega^2} \quad 4$$

$$\Rightarrow y_p(t) = \text{Re}(y_c(t)) = \frac{2}{4-\omega^2} \cos(\omega t) \quad 1$$

So the general solution is

$$y(t) = k_1 \cos(2t) + k_2 \sin(2t) + \frac{2}{4-\omega^2} \cos(\omega t) \quad 3$$

(b) If  $\omega = 3$ , give the solution to the initial value problem

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$$\frac{d^2y}{dt^2} + 4y = 2 \cos(\omega t), \quad y(0) = y'(0) = 0.$$

From above,  $y(0) = k_1 + \frac{2}{4-9} = k_1 - \frac{2}{5}$ ; take  $k_1 = \frac{2}{5}$ .

$y'(0) = 2k_2$ , so take  $k_2 = 0$  2

$$\Rightarrow y(t) = \frac{2}{5} \cos(2t) - \frac{2}{5} \cos(3t) \quad 2$$

(c) Now suppose  $\omega = 2$ . Find the solution to the initial value problem

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$$\frac{d^2y}{dt^2} + 4y = 2 \cos(\omega t), \quad y(0) = y'(0) = 0.$$

Again,  $y_h(t) = k_1 \cos(2t) + k_2 \sin(2t)$ , and again we complexify the equation to  $y'' + 4y = 2e^{i\omega t}$  to find a particular solution. Since  $\omega = 2$ , we try

$$y_c(t) = \alpha t e^{i\omega t} = \alpha t e^{2it} \quad \text{Then}$$

$$y_c'(t) = \alpha e^{2it} + 2i\alpha t e^{2it} \quad \text{and} \quad y_c''(t) = 4i\alpha e^{2it} - 4\alpha t e^{2it}$$

$$\Rightarrow y_c'' + 4y_c = \alpha e^{2it} [4i - 4t + 4t] = \alpha e^{2it} [4i]$$

$$= 4i\alpha e^{2it} \Rightarrow \text{take } \alpha = \frac{2}{4i} = -\frac{i}{2} \quad \left( \begin{array}{l} \text{So} \\ y_p = \text{Re} \\ = \frac{1}{2} t \sin 2t \end{array} \right)$$

$$\Rightarrow y(t) = k_1 \cos(2t) + k_2 \sin(2t) + \frac{1}{2} t \sin(2t)$$

$$y(0) = k_1 \Rightarrow \text{take } k_1 = 0. \quad y'(0) = 2k_2 \Rightarrow k_2 = 0$$

$$\Rightarrow \boxed{y(t) = \frac{t}{2} \sin(2t)} \text{ solves the IVP}$$

(d) Describe the long-term behavior of your solution above, and give a rough sketch.

10 This is resonant forcing: we have oscillations about 0 with period  $\pi$ , and linearly increasing amplitude.

